



QCS051

2.5" Pico-ITX Motherboard
User's Manual

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FCC and DOC Statement on Class B

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio TV technician for help.

Notice:

1. The changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.
2. Shielded interface cables must be used in order to comply with the emission limits.

Table of Contents

Chapter 1 - Introduction.....	6
Specifications	6
Chapter 2 - Hardware Installation.....	8
Board Layout.....	8
Top View.....	8
Bottom View.....	8
Pin Assignment	10
DC-IN (DCCN1).....	10
Battery (BTJ1)	10
Force USB Boot (SWJ1).....	11
USB2.0_1 (UBJ1)	11
USB2.0_2 (UBJ2).....	12
USB2.0_4 (UBJ4)	12
CAN FD (CBJ1)	13
COM1 (TSJ1)	13
USB2.0_ADB (UBCN4).....	14
USB2.0_Debug/Console (DUCN1)	14
Front Panel (FPJ1).....	15
DIO 8-bits (IOJ1).....	15
SPI/I2C/GPIO (IOJ2).....	16
Camera 1 (CMJ1).....	17
Camera 2 (CMJ2).....	18
Expansion Slots.....	19
Installing the M.2 Module	19
Chapter 3 - Software User Guide.....	21
Flash Images with Fastboot.....	21
Software Feature.....	22
Introduction.....	22
Develop Environment	22
General Support.....	22
Linux AP/API Support List.....	22
Ubuntu Support List	23

About this Manual

This manual can be downloaded from the website.

The manual is subject to change and update without notice, and may be based on editions that do not resemble your actual products. Please visit our website or contact our sales representatives for the latest editions.

Warranty

1. Warranty does not cover damages or failures that occur from misuse of the product, inability to use the product, unauthorized replacement or alteration of components and product specifications.
2. The warranty is void if the product has been subjected to physical abuse, improper installation, modification, accidents or unauthorized repair of the product.
3. Unless otherwise instructed in this user's manual, the user may not, under any circumstances, attempt to perform service, adjustments or repairs on the product, whether in or out of warranty. It must be returned to the purchase point, factory or authorized service agency for all such work.
4. We will not be liable for any indirect, special, incidental or consequential damages to the product that has been modified or altered.

Static Electricity Precautions

It is quite easy to inadvertently damage your PC, system board, components or devices even before installing them in your system unit. Static electrical discharge can damage computer components without causing any signs of physical damage. You must take extra care in handling them to ensure against electrostatic build-up.

1. To prevent electrostatic build-up, leave the system board in its anti-static bag until you are ready to install it.
2. Wear an antistatic wrist strap.
3. Do all preparation work on a static-free surface.
4. Hold the device only by its edges. Be careful not to touch any of the components, contacts or connections.
5. Avoid touching the pins or contacts on all modules and connectors. Hold modules or connectors by their ends.



Important:

Electrostatic discharge (ESD) can damage your processor, disk drive and other components. Perform the upgrade instruction procedures described at an ESD workstation only. If such a station is not available, you can provide some ESD protection by wearing an antistatic wrist strap and attaching it to a metal part of the system chassis. If a wrist strap is unavailable, establish and maintain contact with the system chassis throughout any procedures requiring ESD protection.

Safety Measures

- To avoid damage to the system, use the correct AC input voltage range.
- To reduce the risk of electric shock, unplug the power cord before removing the system chassis cover for installation or servicing. After installation or servicing, cover the system chassis before plugging the power cord.

About the Package

The package contains the following items. If any of these items are missing or damaged, please contact your dealer or sales representative for assistance.

- 1 QCS051 Motherboard
- Heat spreader for (Height: 11mm)

The board and accessories in the package may not come similar to the information listed above. This may differ in accordance with the sales region or models in which it was sold. For more information about the standard package in your region, please contact your dealer or sales representative.

Before Using the System Board

When installing the system board in a new system, you will need at least the following internal components.

- Memory module
- Storage device such as a hard disk drive.
- Power supply

External system peripherals may also be required for navigation and display, including at least a keyboard, a mouse and a video display monitor.

Chapter 1 - Introduction

► Specifications

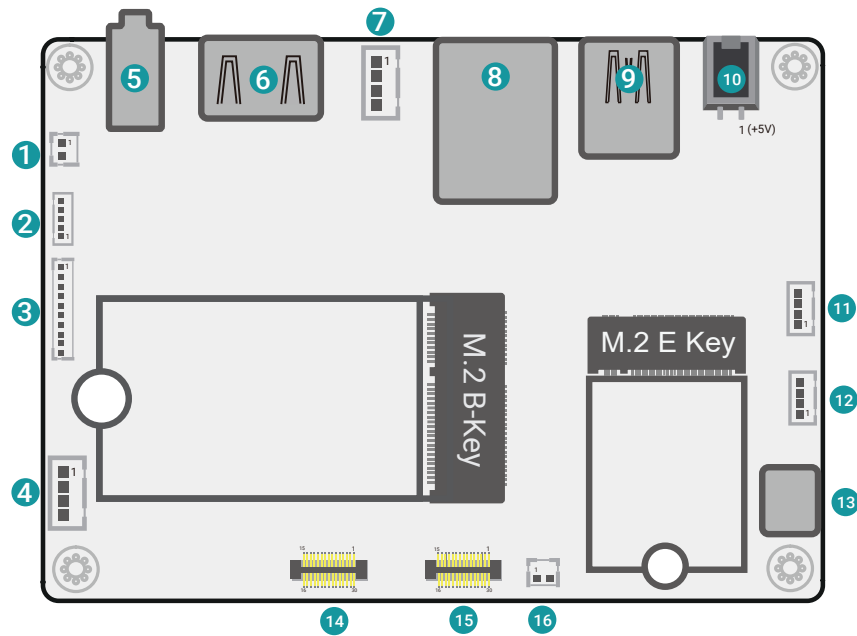
SYSTEM	Processor	QCS6490 Qualcomm® Kryo™ 670, 8 cores, up to 2.7 GHz, 12 TOPS (INT8) QCS5430 (FP1) Qualcomm® Kryo™ 670, 8 cores, up to 2.1 GHz, 3.5 TOPS (INT8)
	Memory	LPDDR5x, 4/8GB
GRAPHICS	Controller	Qualcomm® Adreno™ 643L GPU
	Feature	OpenGL ES 3.2
	Display	1 x HDMI Type A, w/audio. 1080P support on Linux.
	Single Display	HDMI
STORAGE	UFS	Support UFS 3.1, default 128GB
EXPENSION	Interface	1 x M.2 B key 3052 (USB 3.1/ Opt. USB 2.0) reference RM502Q-AE Quectel *Optional USB 2.0 signal with UBJ4
		1 x Nano SIM slot
		1 x M.2 E key 2230 (PCIe x1) reference ENL-Q6856M2 Wifi module
AUDIO	Audio Codec	Audio codec WCD9385
ETHERNET	Controller	AX88179A USB3 to GbE controller
REAR I/O	Ethernet	1 x GbE (RJ-45)
	USB	2 x USB 3.1 Gen1 Type A
	Display	1 x HDMI 1.4
	Audio	1 x Line out/Mic in audio jack
	Debug	1 x Micro USB debug UART
INTERNAL I/O	Serial	1 x RS-232 (COM1, 1x5P/1.00mm)
	USB	3 x USB 2.0 (UBJ1/2/4, 1x4P/1.25mm), UBJ4 could option to M.2 B key 1 x USB Type C (Download only)
	DIO	1 x 8-bit DIO
	CANBus	1 x CAN FD
	SD	1 x uSD3.0 card
	Camera	2 x MIPI-CSI2 for 4-lanes camera, reference to IMX577
	Other I/O	1 x Ext. IO (1*12P/1.25mm), 1 x Power LED, 1 x System LED, 1 x Front Panel 1 x Fan connector (upon request)

POWER	Type	5VDC
	Connector	2 pin Power Jack
	Consumption	Typical: QCS6490: 5V @ 0.6A (3.0Watt) Max.: QCS6490: 5V @ 1.45A (7.25Watt)
	RTC Battery	CR2032 Coin Cell
OS SUPPORT	Linux	Ubuntu 20.04 (Linux Kernel 5.4.233)
ENVIRONMENT	Temperature	Operating: 0°C~60°C, -25°C~75°C Storage: -40 to 85°C
	Humidity	Operating: 5 to 90% RH Storage: 5 to 90% RH
MECHANISM	Dimensions	2.5" Pico-ITX Form Factor: 100mm (3.94") x 72mm (2.83")
	Height	PCB: 1mm Top Side: 16.44mm, Bottom Side: 3.45mm
STANDARDS AND CERTIFICATIONS	Certifications	CE, FCC, RoHS, UKCA

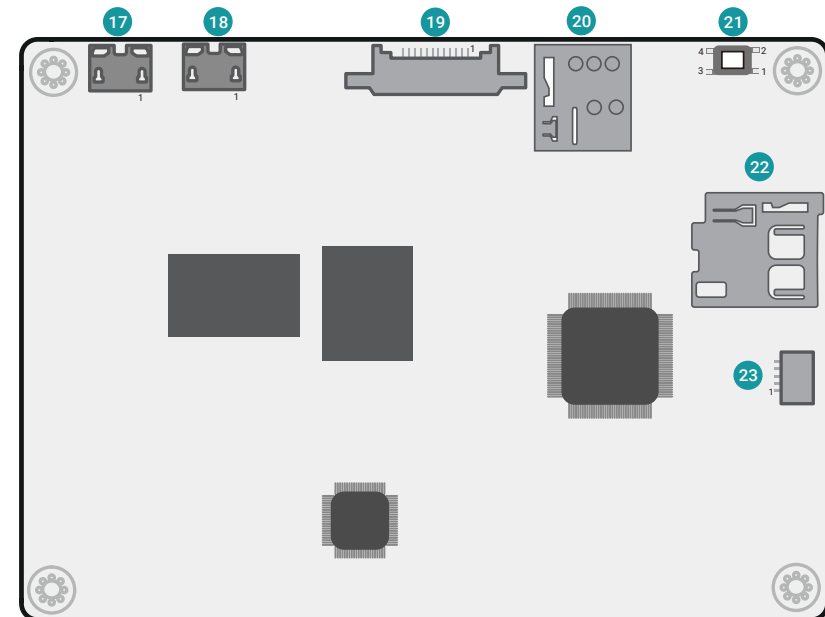
Chapter 2 - Hardware Installation

► Board Layout

Top View



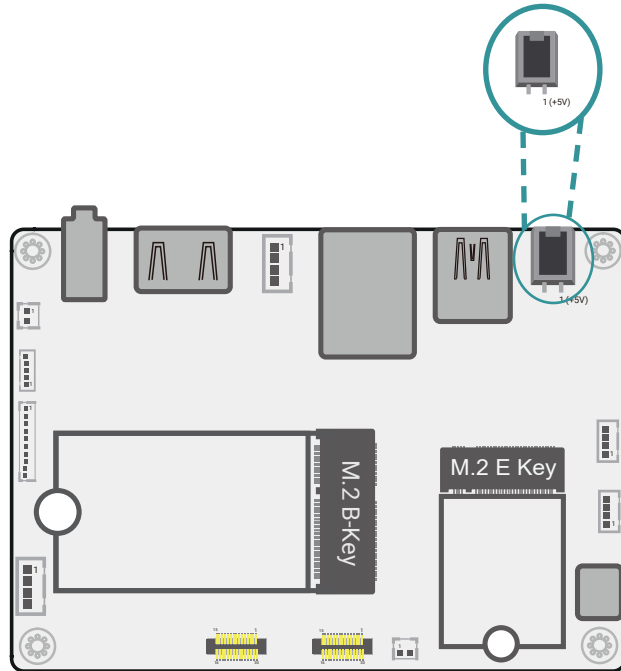
Bottom View



- 1 Battery
- 2 COM1
- 3 DIO 8-bits
- 4 CAN FD
- 5 Audio
- 6 HDMI
- 7 USB2.0_4
- 8 LAN
- 9 USB3.0 Gen1
- 10 DC-IN
- 11 USB2.0_2
- 12 USB2.0_1
- 13 USB Type C (Download only)
- 14 Camera1
- 15 Camera2
- 16 Force USB Boot
- 17 USB2.0_Debug/Console
- 18 USB2.0_ADB
- 19 SPI/I2C/GPIO
- 20 SIM Slot
- 21 USB Boot (SW1)
- 22 uSD Slot
- 23 Front Panel

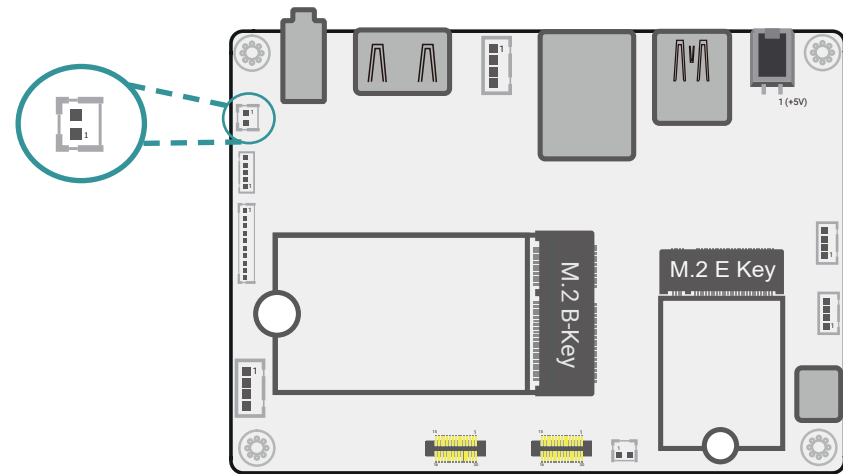
► **Pin Assignment**

DC-IN (DCCN1)



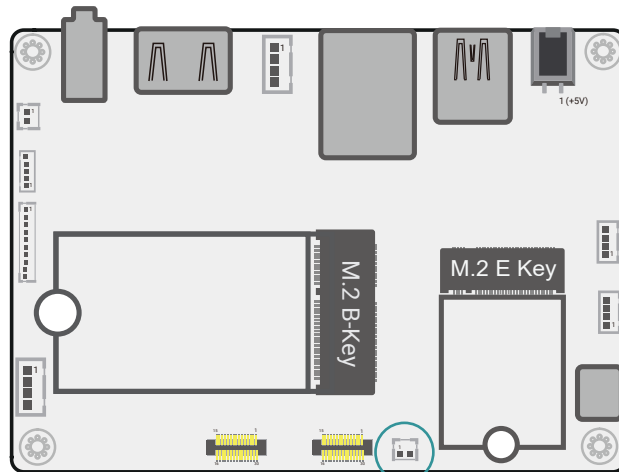
Pin	Assignment
1	+5V
2	GND

Battery (BTJ1)



Pin	Assignment
1	+VBAT
2	GND

Force USB Boot (SWJ1)



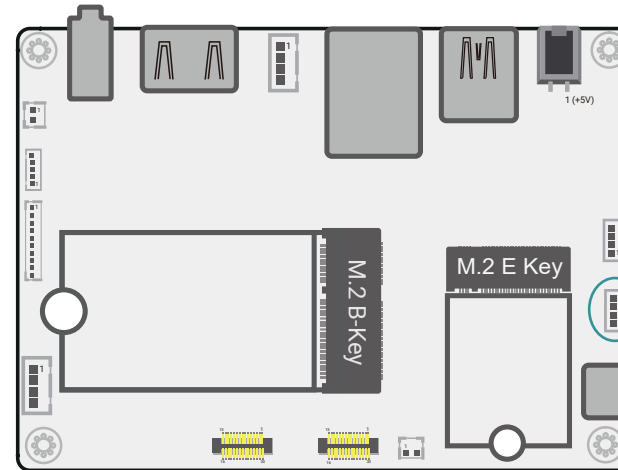
Pin	Assignment
1	Force_USB_Boot
2	SW1_PU_1P8



Note:

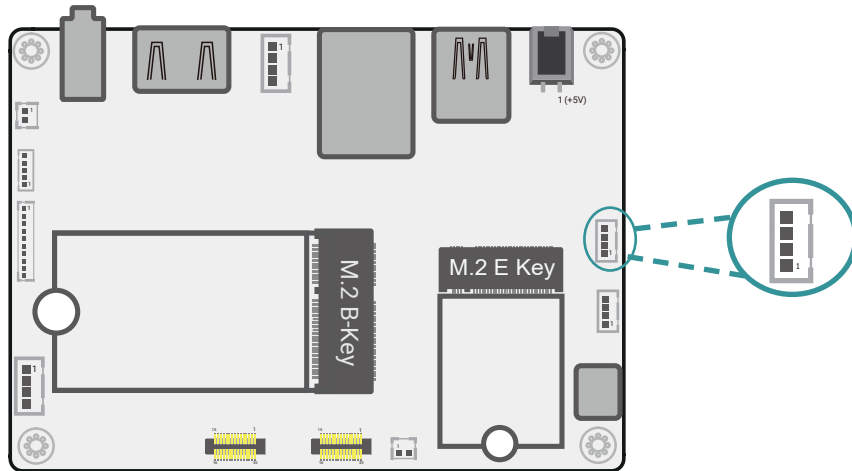
SWJ1, internal wafer, is saved for system integration. Same function as SW1. To enter the download mode (USB Boot), you can just press SW1 or have SWJ1 two pins short-circuited.

USB2.0_1 (UBJ1)



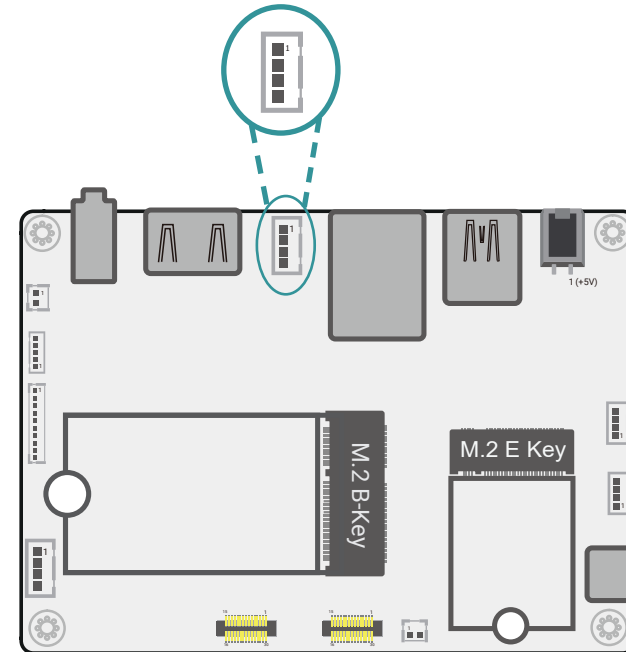
Pin	Assignment
1	+5V
2	USB-DN
3	USB-DP
4	GND

USB2.0_2 (UBJ2)



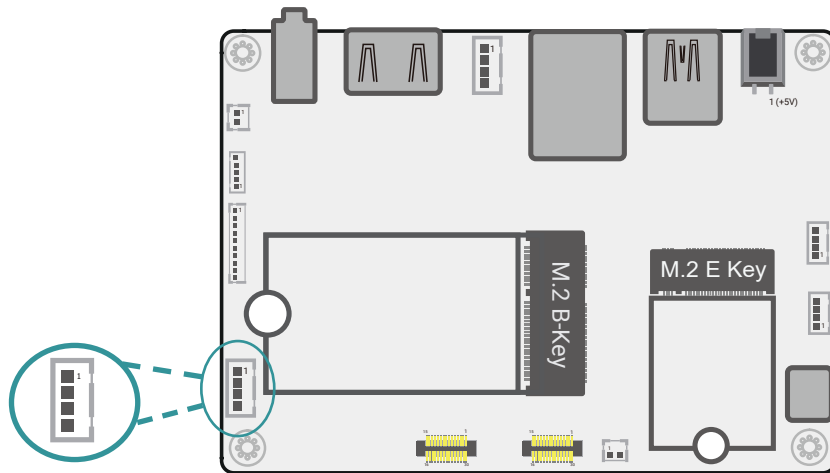
Pin	Assignment
1	+5V
2	USB-DN
3	USB-DP
4	GND

USB2.0_4 (UBJ4)



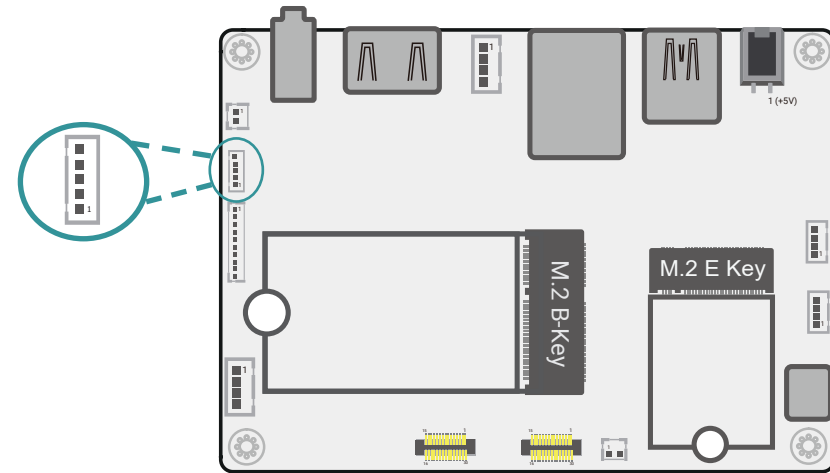
Pin	Assignment
1	+5V
2	USB-DN
3	USB-DP
4	GND

CAN FD (CBJ1)



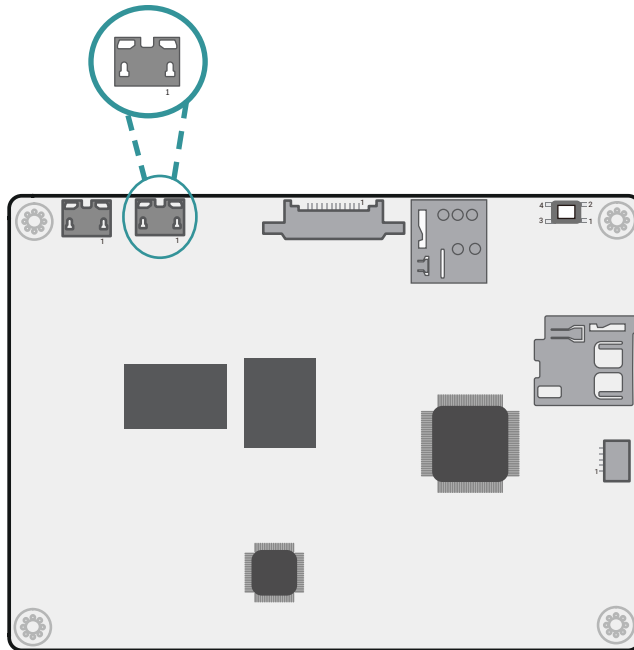
Pin	Assignment
1	+VDD_CAN
2	CAN1H
3	CAN1L
4	GND

COM1 (TSJ1)



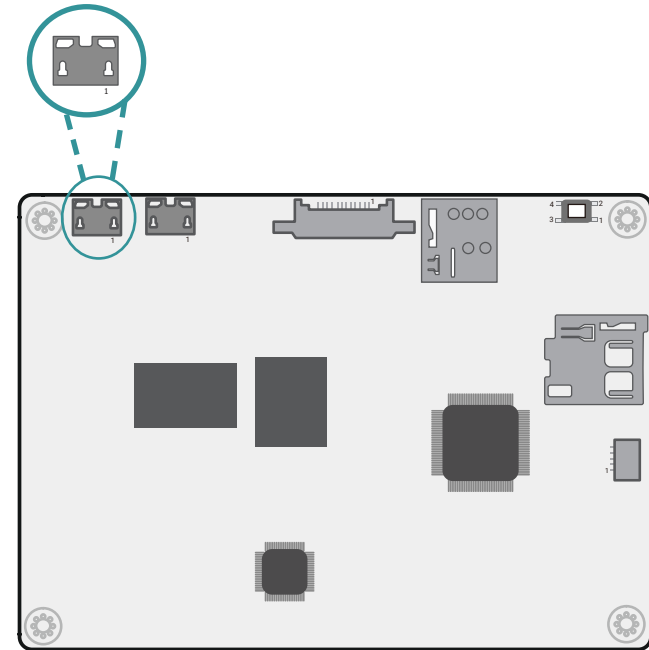
Pin	Assignment
1	COM1_RX
2	COM1_TX
3	COM1_CTS
4	COM1_RTS
5	GND

USB2.0_ADB (UBCN4)



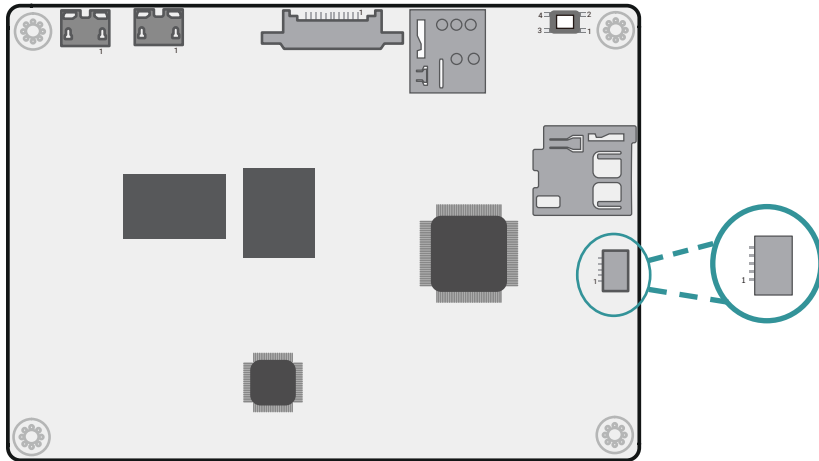
Pin	Assignment
1	+5V
2	USB-DN
3	USB-DP
4	NC
5	GND

USB2.0_Debug/Console (DUCN1)



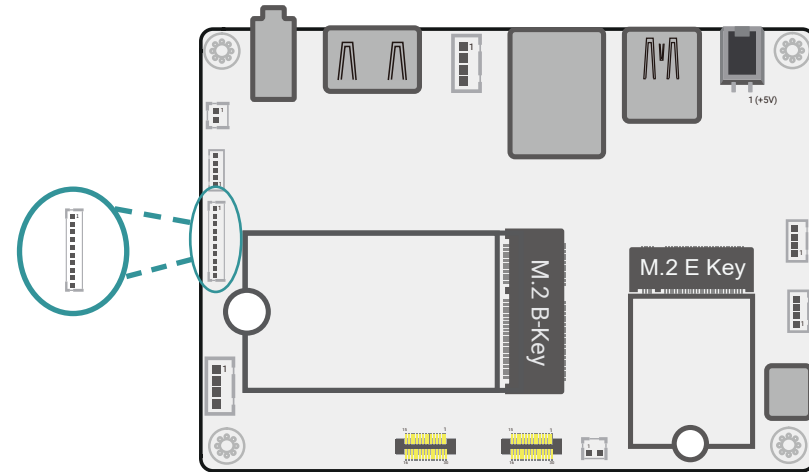
Pin	Assignment
1	+5V
2	USB-DN
3	USB-DP
4	NC
5	GND

Front Panel (FPJ1)



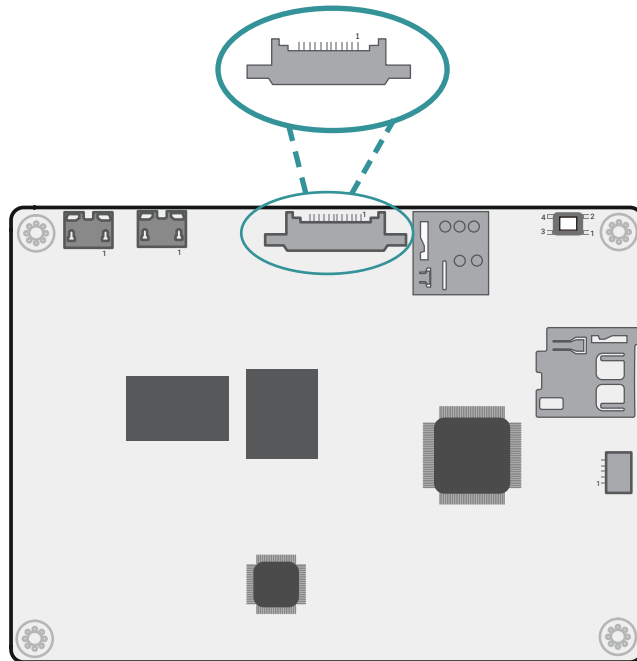
Pin	Assignment
1	GND
2	Volume-_Button#
3	Volume+_Button#
4	PWR_Button#
5	LED_3.3V

DIO 8-bits (IOJ1)



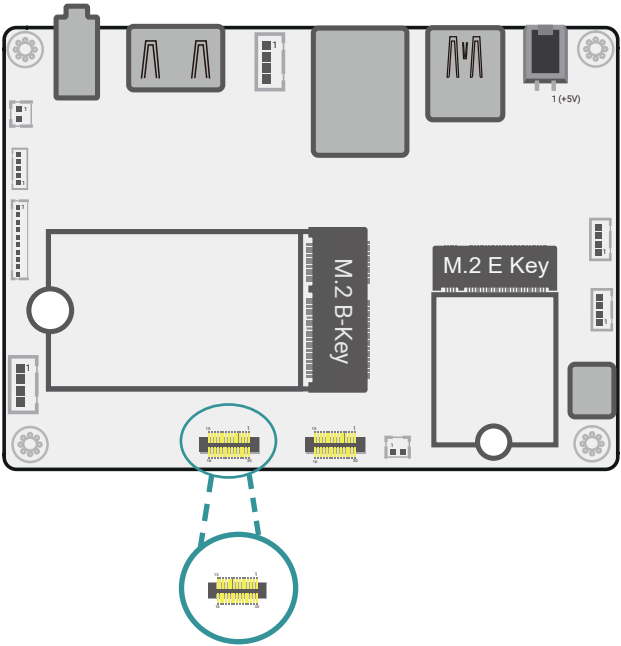
Pin	Assignment
1	DIO0
2	DIO1
3	DIO2
4	DIO3
5	DIO4
6	DIO5
7	DIO6
8	DIO7
9	+VPWR_3.3V
10	GND

SPI/I2C/GPIO (IOJ2)



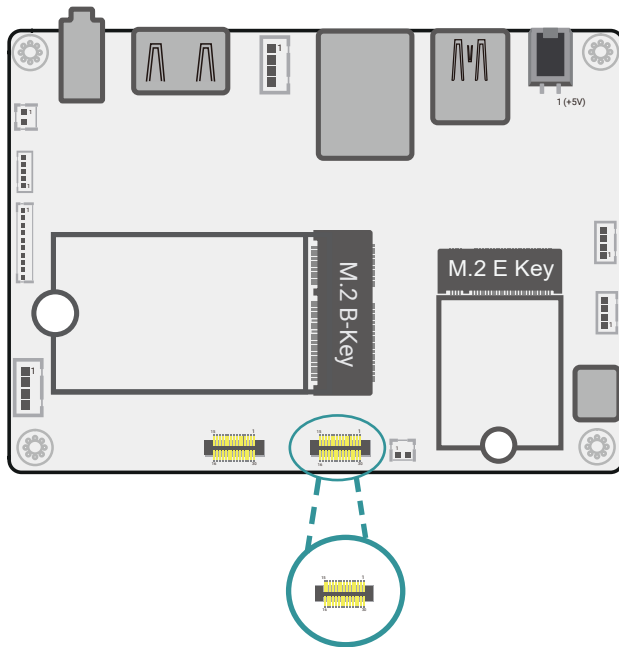
Pin	Assignment
1	+VCC_3.3V
2	SPI_MISO_3V3
3	SPI_MOSI_3V3
4	SPI_CLK_3V3
5	SPI_CS#_3V3
6	I2C_SCL_3V3
7	I2C_SDA_3V3
8	GPIOA_3V3
9	GPIOB_3V3
10	GPIOC_3V3
11	GND
12	GND

Camera 1 (CMJ1)



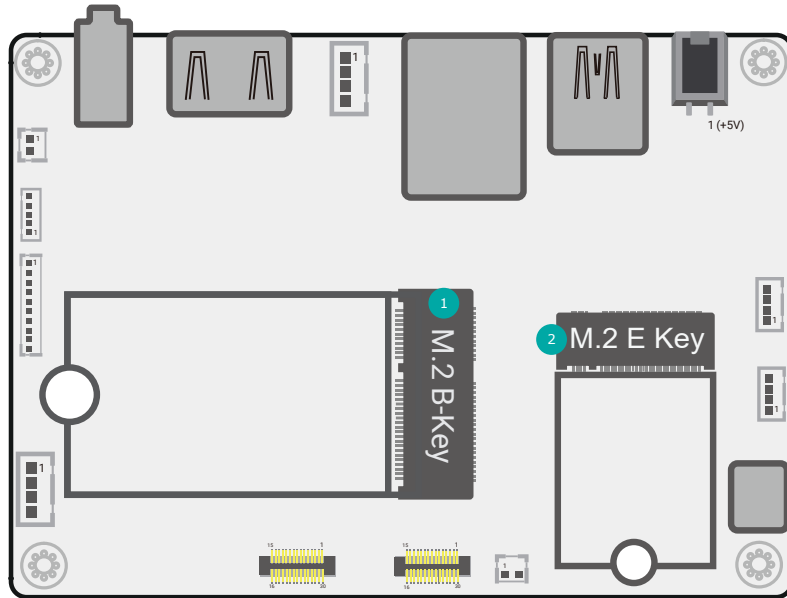
Pin	Assignment	Pin	Assignment
1	CAM2_Strobe/ GPIO	2	CAM2_SPI-CLK
3	+2.8V	4	CAM2_SPI-MOSI
5	CAM2_RESET#	6	GND
7	CAM2_CSI_D2P	8	CAM2_CSI_D2M
9	GND	10	CAM2_CSI_D0P
11	CAM2_CSI_D0M	12	GND
13	CAM2_CSI_D3P	14	CAM2_CSI_D3M
15	Reserved	16	GND
17	CAM2_CSI_D1M	18	CAM2_CSI_D1P
19	GND	20	CAM2_CSI_CKM
21	CAM2_CSI_CKP	22	GND
23	CAM2_CSI_MCLK	24	GND
25	CAM2_I2C-SCL	26	CAM2_I2C-SDA
27	CAM2_SPI-CS#	28	+1.8V
29	CAM2_SPI-MISO	30	+1.1V

Camera 2 (CMJ2)



Pin	Assignment	Pin	Assignment
1	CAM0_Strobe/ GPIO	2	CAM0_RSV#1
3	+2.8V	4	CAM0_RSV#2
5	CAM0_RESET#	6	GND
7	CAM0_CSI_D2P	8	CAM0_CSI_D2M
9	GND	10	CAM0_CSI_D0P
11	CAM0_CSI_D0M	12	GND
13	CAM0_CSI_D3P	14	CAM0_CSI_D3M
15	Reserved	16	GND
17	CAM0_CSI_D1M	18	CAM0_CSI_D1P
19	GND	20	CAM0_CSI_CKM
21	CAM0_CSI_CKP	22	GND
23	CAM0_CSI_MCLK	24	GND
25	CAM0_I2C-SCL	26	CAM0_I2C-SDA
27	CAM0_RSV#4	28	+1.8V
29	CAM0_RSV#3	30	+1.1V

► Expansion Slots



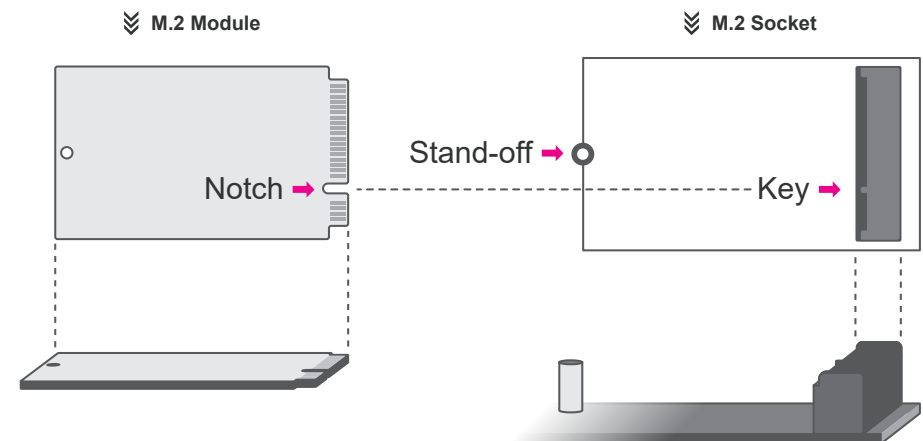
1 M.2 B-Key

2 M.2 E-Key

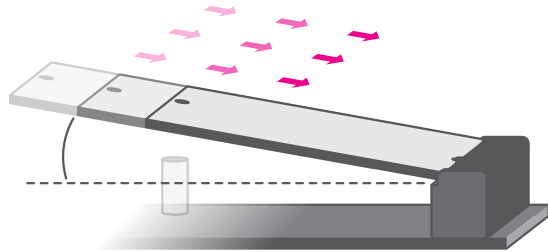
Installing the M.2 Module

Before installing the M.2 module into the M.2 socket, please make sure that the following safety cautions are well-attended.

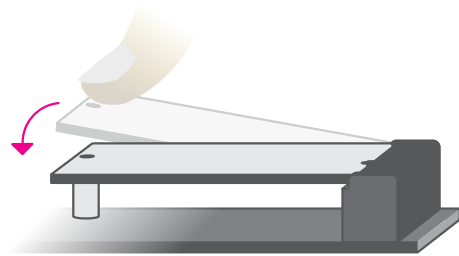
1. Make sure the PC and all other peripheral devices connected to it has been powered down.
2. Disconnect all power cords and cables.
3. Locate the M.2 socket on the system board
4. Make sure the notch on card is aligned to the key on the socket.
5. Make sure the standoff screw is removed from the standoff.



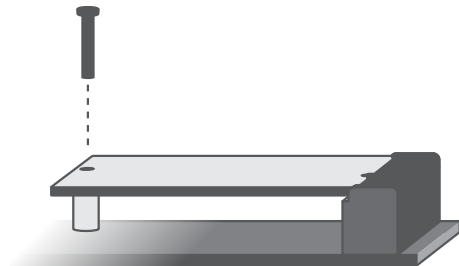
Please follow the steps below to install the card into the socket.



Step 1:
Insert the card into the socket at an angle while making sure the notch and key are perfectly aligned.



Step 2:
Press the end of the card far from the socket down until against the stand-off.



Step 3:
Screw tight the card onto the stand-off with a screw driver and a stand-off screw until the gap between the card and the stand-off closes up. The card should be lying parallel to the board when it's correctly mounted.

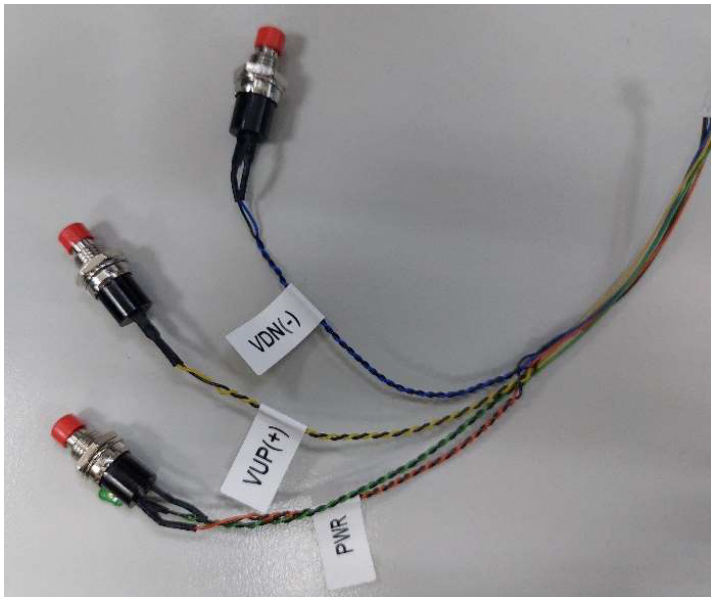
Chapter 3 - Software User Guide

► Flash Images with Fastboot

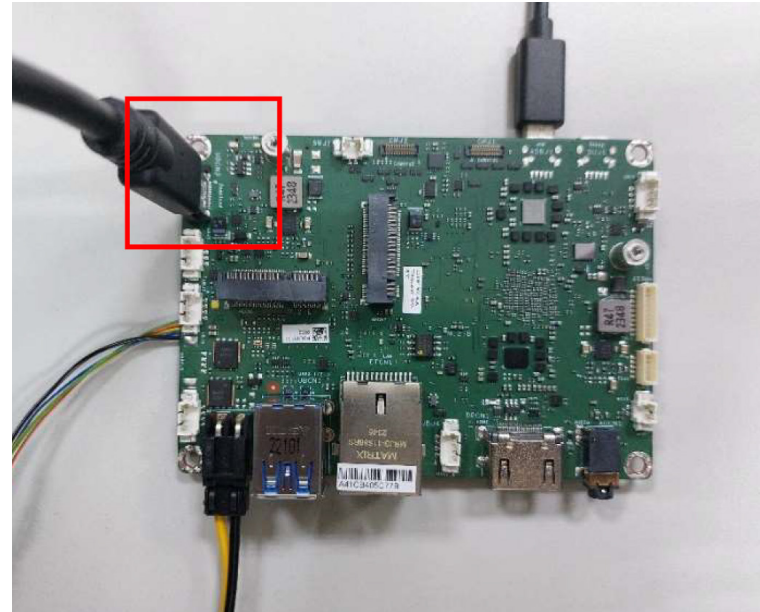
Step 1: Force the device to enter fastboot mode

Enter fastboot mode with VDN- button:

- 1.1. Connect the device to 5 V power supply.
- 1.2. Press and hold the VDN- button.



- 1.3. Connect the device Download port (UBCN3) to the host machine via USB Type-C cable.



Step 2: Flash all images

Follow these steps to flash with fastboot:

- 2.1. Extract qcs051_ubuntu20.04_meta_zzzz_yyyymmdd_xx.zip
- 2.2. Go to the directory <extract_folder>/qcs051_meta/common/build
`$ cd <extract_folder>/qcs051_meta/common/build`
- 2.3. Run the script:
`$ python fastboot_complete.py --skpil=gpt`
- 2.4. Reboot devices after loading complete
`$ fastboot reboot`

Step 3: Flash only HLOS image

Follow these steps to flash only HLOS image:

- 3.1. Bring the board to Fastboot mode. See Section 1.
- 3.2. Enter application processor location and copy abl/boot/sysfs three images to the local folder.
`$ cd <extract_folder>/qcs051_meta/apps_proc/build-qt-dist-ubuntu-fullstack-debug/tmp-glibc/deploy/images/qcs6490-odk`
- 3.3. Run the following commands to flash:
`$ fastboot flash abl abl.elf`
`$ fastboot flash boot qti-ubuntu-robotics-image-qcs6490-odk-boot.img`
`$ fastboot flash system qti-ubuntu-robotics-image-qcs6490-odk-sysfs.ext4`
`$ fastboot reboot`

► Software Feature

Introduction

This section details the Linux operation on Ubuntu 20.04. The OS is an embedded system with Linux kernel 5.4.254. It contains all system-required shell commands and drivers ready.

You can evaluate and develop under Ubuntu 20.04 environment.

Develop Environment

Ubuntu 20.04 kernel 5.4.254 image for QCS051 project was built with PC Ubuntu environment.

General Support

(*) is depended on the Qualcomm support.

Component	Name	Base-Line Feature
General	OS Support	Ubuntu 20.04 (Default Preloaded on UFS), Kernel 5.4.254
Misc	Firmware Upgrade (*)	UUU firmware update tool
	Utilities (*)	Hardware diagnostic utilities

Linux AP/API Support List

(*) is depended on the Qualcomm support.

Component	Description	Detail	Release Schedule
Linux	Ubuntu 20.04 - Kernel 5.4.254	It's an open-source project that delivers a set of tools that create operating system images for embedded Linux systems. Support wayland weston graphics Demo Image Only (*).	2024 Q2
Linux AP/API	Qualcomm QCS6490 20.04 BSP	All library and utility should support (*). Source code package (support by request).	2024 Q2
	Support GPIO	Provide support console for QCS051 platform.	2024 Q2

Ubuntu Support List

(*) is depended on the Qualcomm support.

Component	Support Status
Ubuntu Version	20.04
Kernel version	5.4.254
Window System	X windows
UFS 3.0	Support UFS boot by default, Linux EXT4 file system
Ethernet LAN	Support "ping", "ifconfig" console commands verify, static IP/DHCP Dynamic IP, writable MAC address store in Ethernet IC.
USB	1. Support USB HID Keyboard and Mouse Device. 2. Support USB Mass Storage by "mount" console command, EXT3/EXT4/FAT file system.
USB OTG	Support image download.
HDMI Video	Support max display resolution of 1080p60.
Micro SD Card (uSD card slot)	1. Support SD card boot, support SD storage by "mount" console command, FAT filesystem. 2. Support SD boot (select by boot switch). 3. Not support SDIO module.
GPIO	Support read input high/low status, set output voltage high/low status, controled by Linux device node, 8 pins.
I2C	Support "i2cdetect" console command for detect I2C device.
SPI	TBD
DIO	Support control by Linux device node.
Micro USB debug	Support read Linux kernel debug message by serial port, use PC serial terminal tool (ex. PuTTY), BR 115200.
Play Video	Support play MPEG4(H.264) with GStreamer
Watch Dog	Support watch dog function.
CAN Bus	Support socket CAN TX/RX data.
RTC	Support Linux "date -s"and "hwclock -w" console commands to set system time.
Audio	1. Support system sound output to LINE OUT Connector. 2. Support GStreamer for test play MP3/WAV file. 3. Support sound recorder for test recording audio file.

M.2 B key	<ol style="list-style-type: none"> 1. Support "lsusb" console command for check PCIe card status. 2. Support 5G module: Quectel RM502Q-AE
M.2 2230 E key	<ol style="list-style-type: none"> 1. Support "lspci" console command for check PCIe card status. 2. Support WiFi module: Enli ENL-Q6856M2
MIPI-CSI 1/2 Camera	<ol style="list-style-type: none"> 1. Support camera preview 2. Support camera module: IMX577
Power saving feature (suspend/resume)*	Not support.
WiFi module	<ol style="list-style-type: none"> 1. Support ENL-Q6856M2 module WiFi function only. 2. ENL-Q6856M2 WiFi: <ol style="list-style-type: none"> (1) Support Wifi STA Mode (connect Wifi AP) (2) Not support Soft AP Mode.
5G module	Support Quectel RM502Q-AE module 5G data-link function only.
Image Size	Around ~ 7.3GB (zip file)
Free storage size	Around ~ 92GB free space (/dev/root)